

“Common Fixed Points” for OWC Self-Mappings in S- Spaces

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ABSTRACT

In this paper, we prove a unique common fixed point theorem for OWC (Occasionally Weakly Compatible) four self-mappings in S-spaces (Symmetric spaces). This result is a generalization, improvement of some of the well known comparable results existing in the literature.

AMS subject classifications: 47H10, 54H25.

Keywords: Common fixed point theorem, OWC (Occasionally Weakly Compatible), S-space (Symmetric space).

INTRODUCTION

Before 1968, Banach contraction principle is a fundamental concept in fixed point theory. In 1968, R. Kannan [13] obtained a fixed point theorem for a mapping satisfying contractive condition that need not satisfy continuity. Later on many authors has been extended and improved and generalized these result in different ways (see for e.g. [1- 12 & 14- 15]). Hicks and Rhoades [9] obtained some common fixed point theorems in symmetric spaces and semi metric spaces. And Abbas and Rhoades [6] obtained common fixed point theorems for OWC (Occasionally Weakly Compatible mappings) satisfying a generalized contractive conditions in symmetric spaces. In the present paper, we obtained, a common fixed point theorem for OWC (Occasionally Weakly Compatible) four self-mappings in S-spaces (Symmetric spaces).

PRELIMINARIES

The following definitions are useful in our main theorem and which are due to [6].

Definition 2.1. Two maps A and B are said to be weakly compatible if they commute at coincidence points.

Definition 2.2. Let X be a set, f, g self maps of X . A point x in X is called a coincidence point of f and g iff $fx = gx$. We shall call $w = fx = gx$ a point of coincidence of f and g .

Definition 2.3. Two self maps f, g of a set X . A point x in X are said to be occasionally weakly compatible iff there exists a point x in X which is a coincidence point of f and g at which f and g are commute.

Lemma 2.4. [10]. Let X be a set, f, g are occasionally weakly compatible self-maps of X . If f and g have a unique point coincidence $w = fx = gx$, then w is a unique common fixed point of f and g .
Our results are proved in symmetric spaces, which are more general than metric spaces.

Definition 2.5. Let X be a set. A symmetric on X is a mapping $\rho : X \times X \rightarrow [0, \infty)$ such that $\rho(x, y) = 0$ if and only if $x = y$, and $\rho(x, y) = \rho(y, x)$ for $x, y \in X$. Let $A \in [0, \infty)$, $R_A^+ = [0, A)$. Let $F : R_A^+ \rightarrow \mathbb{R}$ satisfy

- (i) $F(0) = 0$ and $F(t) > 0$ for each $t \in (0, A)$ and
- (ii) F is non decreasing on R_A^+ .

Define, $F\{0, A\} = \{F : R_A^+ \rightarrow \mathbb{R} : F \text{ satisfies (i) - (ii)}\}$.

Let $A \in [0, \infty)$. Let $\psi : R_A^+ \rightarrow \mathbb{R}$ satisfies

- (i) $\Psi(t) < t$ for each $t \in (0, A)$ and
- (ii) Ψ is non decreasing.

Define, $\psi\{0, A\} = \{\psi : R_A^+ \rightarrow \mathbb{R} : \psi \text{ satisfies (i) - (ii) above}\}$.

Some of the examples of mappings $F: R_A^+ \rightarrow R$: F satisfies (i) - (ii), we have refer to [15].

Definition 2.6. A control function Φ is defined by $\Phi: R^+ \rightarrow R^+$ which satisfies $\Phi(t) = 0$ if and only if $t = 0$.

MAIN RESULTS

In this section, we proved, a unique common fixed point theorem for four self-mappings for OWC (Occasionally Weakly Compatible) self-mappings in S-spaces (symmetric spaces).

Theorem 3.1. Let X be a set, ρ a symmetric on X . Let f, g, M and N be four self-mappings of X satisfying the following conditions:

$$(i) \quad F(\Phi(\rho(fu, gv))) \leq \psi(F(K_\Phi(u, v))),$$

$$\text{where, } K_\Phi(u, v) = \text{Max} \{ \Phi(\rho(Mu, Nv)), \Phi(\rho(fu, Mu)) + \Phi(\rho(gv, Nv))/2, \Phi(\rho(fu, Nv)) + \Phi(\rho(gv, Mu))/2 \},$$

$$\text{for each } u, v \in X, F \in F([0, B) \text{ and } \psi \in \psi[0, F((B-0)),$$

where $B = D$ if $D = \infty$ and $B > D$ if $D < \infty$. And

$$(ii) \quad (f, M) \text{ and } (g, N) \text{ are OWC.}$$

Then f, g, M and N are having a unique common fixed point in X .

Proof. Given by (ii) (f, M) and (g, N) are OWC, then there exists two points $u, v \in X$ such that $fu = Mu$ and $gv = Nv$. Suppose that $fu \neq gv$. Then from (i) we get that

$$\begin{aligned} K_\Phi(u, v) &= \text{Max} \{ \Phi(\rho(fu, gv)), \Phi(\rho(fu, fu)) + \Phi(\rho(gv, gv))/2, \Phi(\rho(fu, gv)) + \Phi(\rho(gv, fu))/2 \}, \\ &= \text{Max} \{ \Phi(\rho(fu, gv)), 0, \Phi(\rho(fu, gv)) + \Phi(\rho(gv, fu))/2 \}, \\ &= \text{Max} \{ \Phi(\rho(fu, gv)), \Phi(\rho(fu, gv)) \} \\ &= \Phi(\rho(fu, gv)). \end{aligned} \quad \dots \quad (1).$$

Then by (i) and (1) we get that

$$\begin{aligned} 0 < F(\Phi(\rho(fu, gv))) &< \psi(F(K_\Phi(u, v))) \\ &= \psi(F(\Phi(\rho(fu, gv)))) \\ &< F(\Phi(\rho(fu, gv))), \text{ which is a contradiction.} \end{aligned}$$

Therefore, $\Phi(\rho(fu, gv)) = 0$.

$$\Rightarrow \rho(fu, gv) = 0.$$

$$\Rightarrow fu = gv. \text{ That is, } fu = Mu = gv = Nv.$$

Suppose that there exists another point w such that $fw = Mw$, then using (i) and (1) we get that

$$fw = Mw = gv = Nv = fu = Mu.$$

Hence $z = fu = Mw$ is the unique point of f and M .

By symmetry there exists a unique point $z_1 \in X$ such that $z_1 = gw = Nz_1$.

Then it follows that $z = z_1$,

z is a common fixed point of f, g, M and N and z is unique from condition (i) and (1).

Therefore, f, g, M and N are having a unique common fixed point in X . And this completes the proof of the theorem.

CONCLUSION

Our results are more general than the results of [6].

ACKNOWLEDGMENT

The author is grateful to the reviewers to review this article and giving the valuable suggestions to improve this article.

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